



**Tulsiramji Gaikwad-Patil College of Engineering & Technology, Nagpur**  
(An Autonomous Institution Affiliated to RTM Nagpur University, Nagpur)

**SCHEME OF INSTRUCTION & SYLLABI**

**Programme: Mechanical Engineering**

**Scheme of Instructions: Third Year B.Tech, in Mechanical Engineering Semester-VI (As per NEP 2020)**

Sr. No.	Course Category	Course Code	Course Title	T/P	Contact Hrs / Wk			Credits	Exam Scheme				
					L	P	Hrs		CT-1	CT-2	CA	ESE	TOTAL
1	PCC	BME33601	Internal Combustion Engine	T	3	-	3	3	15	15	10	60	100
2	PCC	BME33602	Mechatronics & Robotics	T	3	-	3	3	15	15	10	60	100
3	HSSM	BME33603	Principles of Industrial Management	T	2	-	2	2	7	8	5	30	50
4	PEC	BME33605-08	Program Elective-II	T	3	-	3	3	15	15	10	60	100
5	PEC	BME33609-12	Program Elective-III	T	3	-	3	3	15	15	10	60	100
6	MDM	BCS33614	Artificial Intelligence	P	-	4	4	2	-	-	25	25	50
7	VSEC	BME33604	Modelling and Simulation using software	P	-	2	2	1	-	-	25	25	50
8	VSEC	BME33605	Modelling and Tool Path Generation using software	P	-	2	2	1	-	-	25	25	50
9	PCC	BME33613	Internal Combustion Engine Lab	P	-	2	2	1	-	-	25	25	50
10	PCC	BME33614	Mechatronics & Robotics Lab	P	-	2	2	1	-	-	25	25	50
<b>Total</b>					<b>14</b>	<b>12</b>	<b>26</b>	<b>20</b>	<b>67</b>	<b>68</b>	<b>170</b>	<b>395</b>	<b>700</b>

L-Lecture

SL-Self Learning

P-Practical

NHL-Notional Hrs/Wk(Total Notional Hrs)

CT1-ClassTest1

TA/CA-Teacher Assessment Continuous Assessment

CT2-ClassTest2

ESE-End Semester Examination (For Laboratory End Semester Performance)




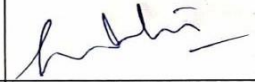
Course Category	PCC (Program Core Courses)	PEC (Program Elective Courses)	(MDM) Multidisciplinary Minor	OEC (Open Elective courses from other discipline)	VSEC (Vocational and Skill Enhancement Course)	HSSM (Humanities Social Science and management) (VEC/IKS/AEC)	FP/CP/OJT/RM/ Project (Experimental Learning Courses)
Credits	8	6	2	-	2	2	-
Cumulative Sum	40	10	11	8	8	14	2


**PROGRESSIVE TOTAL CREDITS: 106+20=124**

				Nov, 2025	1.00	Applicable for AY 2025-26 Onwards
Chairperson	Dean Academics	Vice Principal	Principal	Date of Release	Version	
Mechanical Engineering (NBA Accredited) Tulsiramji Gaikwad-Patil College of Engineering and Technology, Nagpur			Vice Principal (Academics) Dr. Premanand Naktode		Principal TGP CET, NAGPUR	

**Program: Mechanical Engineering**  
List of **Program Electives** offered By Mechanical Department (NBA Accredited)

Program Elective-I	Program Elective-II	Program Elective-III	Program Elective-IV	Program Elective-V
<b>Semester V</b>	<b>Semester VI</b>	<b>Semester VI</b>	<b>Semester VII</b>	<b>Semester VIII</b>
BME33504: Industrial Economics and Management	BME33605: Hydraulic and Pneumatic Systems	BME33609: Finite Element Method	BME34704: Total Quality Management	BME34803: Material Handling System
BME33505: Computer Aided Design	BME33606: Mechanical Measurement and Metrology	BME33610: Advanced Manufacturing Techniques	BME34705: Finite Element Analysis	BME34804: Computer Integrated Manufacturing
BME33506: Automotive System	BME33607: Ginning Process	BME33611: Operation Research	BME34706: Design of Mechanical drives	BME34805: Renewable Energy System
BME33507: Smart Manufacturing	BME33608: Control System Engineering	BME33612: Industrial Robotics	BME34707: Advanced Mechanical Vibration	BME34706: Composite and Nano Materials

				Nov ,2025	1.00	Applicable for AY 2025-26 Onwards
<b>Chairperson</b>	<b>Dean Academics</b>	<b>Vice Principal</b>	<b>Principal</b>	<b>Date of Release</b>	<b>Version</b>	


**Chairperson**  
 Mechanical Engineering (NBA Accredited)

**Dean Academics**  
 Tulsiramji Gaikwad Patil College of Engineering and Technology, Nagpur

**Vice Principal (Academics)**  
 TGPCET, NAGPUR

**Principal**  
 Dr. Premanand Naktode  
 TGPCET, Nagpur



**Third Year (Semester-VI) B. Tech. Mechanical Engineering**

**BME33601: Internal Combustion Engine**

Teaching Scheme		Examination Scheme	
Lectures	3Hr/Week	CT	30 Marks
Tutorials	-	CA	10 Marks
Total Credits	3	ESE	60 Marks
		<b>Total</b>	100 Marks
		Duration of ESE:03Hrs	

**Course Objectives:**

1	To learn the concept of IC Engine
2	To understand the concept of fuel supply and engine lubrication
3	To apply the basic knowledge of ignition in IC engine
4	To analyze the testing and performance of IC engine
5	To understand recent advances in IC engine

**Course Contents**

	Course Contents	Hours
<b>Unit I</b>	<b>Introduction:</b> Introduction, Engine Classification, components of I. C. Engines, Two stroke SI and CI engines, Four stroke SI and CI engines, Comparison of SI and CI Engines, valve and port timing diagram. Advantages and disadvantages, applications.	<b>(9)</b>
<b>Unit II</b>	<b>Fuels and its supply system for IC Engines:</b> Important qualities of IC engine fuels, rating of fuels, Carburetion, mixture requirement for different loads and speeds, simple carburetor and its working, types of carburetors, MPFI, types of injection systems in CI engine, fuel pumps and injectors, types of nozzles, spray formation. <b>Engine cooling and lubrication:</b> Necessity of engine cooling, disadvantages of overcooling, Cooling systems and their comparison, Air cooling, Liquid cooling, types of lubricants and their properties, SAE rating of lubricants, Types of lubrication systems, Supercharging/Turbo-charging: Objectives, Limitations, Methods and Types, Different arrangements of turbochargers and superchargers	<b>(9)</b>
<b>Unit III</b>	<b>Ignition and Combustion in IC Engines:</b> Function of Ignition system, Battery and Magneto Ignition system, Electronic Ignition system, Spark plug and its types, Firing order, Types of combustion chambers in SI and CI engines, Stages of combustion in SI engines, abnormal combustion and knocking in SI engines, factors affecting knocking, effects of knocking, control of knocking, combustion chambers for SI engines, Stages of combustion in CI engines, detonation in C.I. engines, factors affecting detonation, controlling detonation, engine emission	<b>(9)</b>
<b>Unit IV</b>	<b>Testing and Performance of IC Engine:</b> Measurement of Indicated power, brake power, Friction Power, Willan's Line Method, Morse Test, Motoring Test, Dynamometers, indicated thermal efficiency, brake thermal efficiency and volumetric efficiencies, performance maps, Engine testing standards, heat balance sheet.	<b>(9)</b>

<b>Unit V</b>	<b>Recent Trends in IC Engines:</b> LHR engines, lean burn engines, stratified charge spark ignition engine, homogeneous charge compression ignition, reactivity-controlled compression ignition, six stroke engine concept, Electric Vehicle, hybrid engine vehicle, Hydrogen Internal Combustion Engine.	<b>(9)</b>
<b>Text Books</b>		
T.1	Internal Combustion Engine by V Ganeshan, McGraw Hill Education Pvt. Ltd.	
T.2	Internal Combustion Engine by R. K. Rajput, Laxmi Publication	
<b>Reference Books</b>		
R.1	Internal Combustion Engines, E. Obert, Intex educational publication.	
R.2	Internal Combustion Engine fundamental by John Heywood, Tata MCGraw Hill Publication	

<b>UsefulLinks</b>	
1	<a href="https://nptel.ac.in/courses/112104033">https://nptel.ac.in/courses/112104033</a>
2	<a href="https://nptel.ac.in/courses/112103262">https://nptel.ac.in/courses/112103262</a>

	<b>Course Outcomes</b>	<b>CL</b>
<b>BME33601.1</b>	<b>Interpret</b> the principles of IC engines, including valve and port timing diagrams, to know advantages, disadvantages, and applications.	3
<b>BME33601.2</b>	<b>Apply</b> the concepts of engine cooling and lubrication systems to enhance the performance and reliability of internal combustion engines.	3
<b>BME33601.3</b>	<b>Explain</b> the function of ignition systems in SI and CI engines, including factors that influence knocking and abnormal combustion.	4
<b>BME33601.4</b>	<b>Calculate</b> SI and CI engine performance, including emission factors affecting knocking and detonation.	3
<b>BME33601.5</b>	<b>Illustrate</b> recent trends in IC engines to gain advantages, disadvantages, and challenges.	3



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### Third Year (Semester-VI) B. Tech. Mechanical Engineering

#### BME33602: Mechatronics & Robotics

Teaching Scheme		Examination Scheme	
Lectures	3Hr/Week	CT	30
Tutorials	-	CA	10
Total Credits	3	ESE	60
		<b>Total</b>	100 Marks
		Duration of ESE: 03 Hrs	

#### Course Objectives:

1	To introduce students to the fundamental concepts of Mechatronics systems and its interdisciplinary nature
2	To develop programming skills for automation using PLCs and design ladder logic diagrams for real-time systems.
3	To familiarize students with Supervisory controlled Data acquisition system along with virtual instrumentation as a tool for real-time monitoring and control in modern industries.
4	To develop foundational knowledge for robot hardware, design and integration
5	To Understand different methods used for programming robots.

#### Course Contents

Course Contents		Hours
<b>Unit I</b>	Introduction to Mechatronics Systems, Scope and Elements of Mechatronics, Mechatronics Design Process, Sensors, Integrated Circuits and Actuators, Control Systems, Close loop and open loop control system,  <b>Case Studies on Mechatronics Systems</b> such as Temperature Controller, High-Speed Tilting Trains, Antilock Braking System (ABS), Engine Management System, Smart Irrigation System for Drought-Prone Regions, Smart HVAC (Heating, Ventilation, and Air Conditioning) System.	<b>(9)</b>
<b>Unit II</b>	<b>Programmable Logic Controller (PLCs)</b> , Basic structure of PLC, Principle of operation of PLC, PLC programming languages, ladder diagram, latching, timer, counters, Selection criteria of PLC.  <b>Application of PLC:</b> Extending and retracting a pneumatic piston using latches, control of two pneumatic pistons, Smart Elevator Control, Conveyor Belt with Object Sorting, Automatic Water Tank Level Controller.	<b>(9)</b>
<b>Unit III</b>	<b>Data Acquisition Systems (DAQ)</b> , Components of DAQ, Role of DAQ in real-time control and monitoring.  <b>Virtual Instrumentation (VI):</b> Its need, Tools use for Virtual Instrumentation, Software use for Virtual Displays (e.g. LabView, MATLAB etc), Real-Time Monitoring and Control, Traditional methods of monitoring and control, Cloud-based Monitoring Systems, Edge-based Real-Time Systems.  <b>Supervisory Control and Data Acquisition (SCADA):</b> As an Extension of DAQ, SCADA functions (Data visualization, alarm management, logging, and supervisory control), Stand alone DAQ vs SCADA, Communication Protocol of SCADA (e.g. MODBUS, OPC, Ethernet/IP)	<b>(9)</b>

<b>Unit IV</b>	<b>Introduction to Robotics and Robotic Components:</b> <b>Types of Robots:</b> Cartesian, Cylindrical, Articulated, SCARA, Delta, Mobile Robots. <b>Basic Components of a Robot:</b> Manipulator/Arm, End-effector (grippers, tools), Actuators (Electric, Pneumatic, Hydraulic), Sensors (Proximity, Vision, Force, IR, Ultrasonic), Controller (Microcontroller/PLC-based). <b>Robot Drive Systems:</b> Servo, Stepper, DC drives	<b>(9)</b>
<b>Unit V</b>	<b>Robot Programming and Applications:</b> <b>Robot Programming Methods:</b> Manual Teach, Lead-through, Offline programming, PLC programming (intro to simulation tools like RoboDK or MATLAB Robotics Toolbox). <b>Safety in Robotics:</b> Safety sensors, emergency stops, safety standards (ISO 10218). <b>Robotics Applications: Industrial:</b> Welding, Painting, Pick and Place, Assembly, Inspection. <b>Emerging:</b> Agriculture, Medical Surgery, Defense, Warehouse Automation	<b>(9)</b>

#### Text Books

T.1	Mechatronics Borole,Rajesh P;Angal,Yogesh S;Patil,Varsha K., Nirali Prakashan, 4th Edition, 2005
T.2	Mechatronics Integrated Mechanical Ramachandran K.P., Willey.
T.3	Boltan W, Mechatronics : Pearson Education, 11th Edition, 2005

#### Reference Books

R.1	Introduction to Mechatronics and Measurement Systems , David Alciators & Michael B. Histan, Tata McGraw Hills, India
R.2	Mechatronics : HMT LTD, McGraw-Hill

#### Useful Links

1	<a href="https://nptel.ac.in/courses/112103174">https://nptel.ac.in/courses/112103174</a>
2	<a href="https://nptel.ac.in/courses/112107298">https://nptel.ac.in/courses/112107298</a>

	Course Outcomes	CL
<b>BME33602.1</b>	<b>Explain</b> feedback control in Mechatronics systems to determine real-time case studies.	4
<b>BME33602.2</b>	<b>Summarize</b> ladder logic programs using timers for recent applications in Programmable Logic Controllers.	5
<b>BME33602.3</b>	<b>Interpret</b> data acquisition and SCADA systems for real-time industrial monitoring.	3
<b>BME33602.4</b>	<b>Classify</b> robots based on configuration to find requirements in specific applications.	4
<b>BME33602.5</b>	<b>Differentiate</b> robot programming methods to know safety protocols, design, and robot programming techniques.	4



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**Third Year (Semester-VI) B. Tech. Mechanical Engineering**

**BME33603: Principles of Industrial Management**

Teaching Scheme		Examination Scheme	
Lectures	2 Hr/Week	<b>CT</b>	15 Marks
Tutorials	-	<b>CA</b>	5 Marks
Total Credits	2	<b>ESE</b>	30 Marks
		<b>Total</b>	50 Marks
			Duration of ESE: 02Hrs

**Course Objectives:**

1	To understand the significance of various management skills in different organizational contexts.
2	To understand the different types of plant layouts.
3	To understand comprehension of material requirement planning (MRP) and storekeeping procedures by explaining their underlying principles, processes, and objectives

**Course Contents**

	Course Contents	Hours
<b>Unit I</b>	<p><b>Basics of industrial Management</b>            Management - Definition-Administration-Definition-Henry-Fayol's principles of management- Business Organization- Types- Proprietorship- Partnership- Joint stock- Cooperative Society-Advantages and disadvantages -Functions of Management - Planning Definition-Functions- Organization- Definition- types of organization -Line-Functional-Line &amp; staff-advantages and disadvantages- Leadership -Types -Quality of good leader Motivation - Maslow's Theory of Motivation -Hierarchy of needs-Communication - Process of Communication - Barriers for effective communication.</p>	<b>(9)</b>
<b>Unit II</b>	<p><b>Production management</b>            Concept of project work - Project planning -Market survey- Project capacity- selection of site for project- Plant layout-Types of Plant layout- Product design- Stages in product design drawing-Specifications-Material requirement-operation- Planning-Production- definition-Job, Batch &amp; Mass production with their advantages and disadvantages- Productivity-definition factors to improve productivity- Production planning and Control (PPC)-definition-Functions of PPC- planning, routing, scheduling, dispatching and Inspection-Introduction to CPM and PERT -Comparison.</p>	<b>(9)</b>
<b>Unit III</b>	<p><b>Materials management</b>            Material management - definition, functions- Purchase - Objectives, different methods of purchasing -Purchase procedure-Comparative statement-purchase order-Tender-Types of tender- Store keeping- classification of stores - Functions of store keeper. Store management Bin Card - Material Issue Requisition-Material Returned Note- Store ledgers -Codification of stores-Inventory Management- Definition - functions of Inventory Control- Advantages of Inventory Control Enterprise resource planning - concept, features and applications.- Material Requirement Planning (MRP)-concept, applications -Justin Time (JIT)-concept and benefits-Supply chain management-concept and benefits -FIFO(first in first out) concept-definition.</p>	<b>(9)</b>

Text Books	
T.1	Industrial Organization and Engineering Economics T.R. Banga & S.C. Sharma Khanna. Publishers
T.2	Industrial management and engineering economics O.P. Khanna Khanna. Publishers
Reference Books	
R.1	Industrial management and organizational behavior K.K. Ahuja

Useful Links	
1	<a href="http://www.youtube.com/watch?v=SF53ZZsP4ik">www.youtube.com/watch?v=SF53ZZsP4ik</a>
2	<a href="http://www.youtube.com/watch?v=iPZIQ3Zx5zc">www.youtube.com/watch?v=iPZIQ3Zx5zc</a>

	Course Outcomes	CL
<b>BME33603.1</b>	<b>Explain</b> the importance of management functions in industrial settings to gain knowledge of their impact on organizational performance.	4
<b>BME33603.2</b>	<b>Apply</b> knowledge of plant layouts to determine product design stages to real-world production scenarios.	3
<b>BME33603.3</b>	<b>Define</b> Materials Management and explain its purpose, scope, and importance in engineering and industry.	3



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**Third Year (Semester-VI) B. Tech. Mechanical Engineering**

**BME33605: (PE-II) Hydraulic And Pneumatic Systems**

Teaching Scheme		Examination Scheme	
Lectures	3 Hr/Week	CT	30 Marks
Tutorials	-	CA	10 Marks
Total Credits	3	ESE	60 Marks
		Total	100 Marks
		Duration of ESE:03Hrs	

**Course Objectives:**

1	Students will understand the Fundamentals of fluid power
2	Students will analyze and design Systems of hydraulic system
3	Students will apply Practical Skills Pneumatic system

**Course Contents**

**Hours**

<b>Unit I</b>	<b>Fluid Power Principles And Hydraulic Pumps</b> Introduction to Fluid power – Advantages and Applications – Fluid power systems – Types of fluids – Properties of fluids and selection – Basics of Hydraulics – Pascal's Law – Principles of flow – Friction loss – Work, Power and Torque Problems, Sources of Hydraulic power : Pumping Theory – Pump Classification – Construction, Working, Design, Advantages, Disadvantages, Performance, Selection criteria of Linear and Rotary – Fixed and Variable displacement pumps – Problems.	<b>(9)</b>
<b>Unit II</b>	<b>Hydraulic Actuators And Control Components</b> Hydraulic Actuators: Cylinders – Types and construction, Application, Hydraulic cushioning – Hydraulic motors – Control Components: Direction Control, Flow control and pressure control valves – Types, Construction and Operation – Servo and Proportional valves – Applications – Accessories: Reservoirs, Pressure Switches – Applications – Fluid Power ANSI Symbols – Problems.	<b>(9)</b>
<b>Unit III</b>	<b>Hydraulic Circuits And Systems</b> Accumulators, Intensifiers, Industrial hydraulic circuits – Regenerative, Pump Unloading, Double-Pump, Pressure Intensifier, Air-over oil, Sequence, Reciprocation, Synchronization, Fail-Safe, Speed Control, Hydrostatic transmission, Electro hydraulic circuits, Mechanical hydraulic servo systems.	<b>(9)</b>
<b>Unit IV</b>	<b>Pneumatic And Electro Pneumatic Systems</b> Properties of air – Perfect Gas Laws – Compressor – Filters, Regulator, Lubricator, Muffler, Air control Valves, Quick Exhaust Valves, Pneumatic actuators, Design of Pneumatic circuit – Cascade method – Electro Pneumatic System – Elements – Ladder diagram – Problems, Introduction to fluidics and pneumatic logic circuits.	<b>(9)</b>
<b>Unit V</b>	<b>Trouble Shooting And Applications</b> Installation, Selection, Maintenance, Trouble Shooting and Remedies in Hydraulic and Pneumatic systems, Design of hydraulic circuits for Drilling, Planning, Shaping, Surface grinding, Press and Forklift applications. Design of Pneumatic circuits for Pick and Place applications and tool handling	<b>(9)</b>

	n CNC Machine tools – Low cost Automation – Hydraulic and Pneumatic power packs.	
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**Text Books**

T.1	Majumdar S.R., “Pneumatic systems – Principles and maintenance”, Tata McGraw Hill, 1995
T.2	Anthony Lal, “Oil hydraulics in the service of industry”, Allied publishers, 1982.
T.3	Anthony Esposito, “Fluid Power with Applications”, Pearson Education 2000.

**Reference Books**

R.1	Harry L. Stevart D.B, “Practical guide to fluid power”, Taraoeala sons and Port Ltd. Broadey, 1976.
R.2	Majumdar S.R., “Oil Hydraulics”, Tata McGraw-Hill, 2000.
R.3	Dudelyt, A. Pease and John T. Pippenger, “Basic Fluid Power”, Prentice Hall, 1987.

**Useful Links**

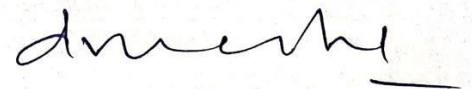
1	<a href="https://archive.nptel.ac.in/courses/112/106/112106300/">https://archive.nptel.ac.in/courses/112/106/112106300/</a>
2	<a href="https://archive.nptel.ac.in/courses/112/105/112105047/">https://archive.nptel.ac.in/courses/112/105/112105047/</a>

	<b>Course Outcomes</b>	<b>CL</b>
<b>BME33605.1</b>	<b>Summarize</b> the fundamentals of fluid power to determine hydraulic system design requirements.	4
<b>BME33605.2</b>	<b>Select</b> appropriate hydraulic control components, to achieve desired system performance	4
<b>BME33605.3</b>	<b>Analyze</b> hydraulic system designs, to determine performance, stability, and control.	4
<b>BME33605.4</b>	<b>Apply</b> pneumatic and electro-pneumatic principles to find out troubleshoot circuits using air control valves,	3
<b>BME33605.5</b>	<b>Explain</b> troubleshooting techniques and remedies for common issues in hydraulic and pneumatic systems,	4



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**Third Year (Semester-VI) B. Tech. Mechanical Engineering**

**BME33606: (PE-II) Mechanical Measurement and Metrology**

Teaching Scheme		Examination Scheme	
Lectures	3 Hr/Week	CT	30 Marks
Tutorials	-	CA	10 Marks
Total Credits	3	ESE	60 Marks
		Total	100 Marks
		Duration of ESE:03Hrs	

**Course Objectives:**

1	Understand the basic structure and principles of measuring system
2	Explore various sensing and signal conditioning elements used in measurement systems
3	Familiarize students with the instruments used for measuring pressure, displacement, force, torque and power
4	To understand standards of measurement, linear and angular measurement methods, and precision tools.
5	Provide knowledge on limits and fits, gauges and advanced inspection tools for precision engineering

**Course Contents**

**Hours**

<b>Unit I</b>	Purpose, structure and elements of measuring system. Static characteristics of measurement system, elements including systematic, statistical characteristics, generalized model of system elements and calibration. Error measurement, error probability density function, error reduction. Introduction to dynamic characteristics of measurement system. Introduction to noise in measurement system.	<b>(9)</b>
<b>Unit II</b>	Classification, Principle, Sensing elements, Signal conditioning elements, Construction, Range and working of instruments for measurement of Linear and Angular Displacement, Speed, Load, Strain, Force, Torque and Power. (Analytical treatment not included)	<b>(9)</b>
<b>Unit III</b>	Classification, Principle, Sensing elements, Signal conditioning elements, Construction, Range and working of instruments for measurement of Pressure, Vacuum, Sound, Light and Temperature. (Analytical treatment not included)	<b>(9)</b>
<b>Unit IV</b>	Standards of Measurement, Line, End and Wavelength standard, Working standards, Requirement of interchangeability, Allowance and Tolerance, Selective assembly, Measurement of Straightness and Flatness. Instruments for Linear and Angular Measurement. (Vernier, Angle gauge, Sine bar, Level indicator, Clinometers and Taper gauge)	<b>(9)</b>
<b>Unit V</b>	Limits and Fits, Tolerance analysis of Limits and Fits, Types of limit gauges, Types of fit, Shaft and Hole basis system, Design of Limit gauge and Process planning sheet (Numerical treatment is expected). Comparators: Mechanical, Optical, Electrical, Electronic, Pneumatic. Study and use of Optical profile projectors, Tool maker's microscope and Autocollimator. Measurement of	<b>(9)</b>

	Screw thread and Gear tooth.	
<b>Text Books</b>		
T.1	Mechanical Measurement and Control, D.S. Kumar, Metropolitan Book Co	
T.2	Metrology, R. K. Jain, Khanna Publishers	
T.3	Instrumentation Measurement and Analysis, B.C. Nakra, K.K. Choudhary, TMH	
<b>Reference Books</b>		
R.1	Principles of Measurement Systems, John P. Bentley, Pearson	
R.2	Metrology and Measurement, Anand K. Bewoor, Vinay A. Kulkarni, TMH	

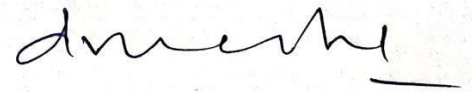
<b>Useful Links</b>	
1	<a href="https://nptel.ac.in/courses/112104250">https://nptel.ac.in/courses/112104250</a>
2	<a href="https://nptel.ac.in/courses/112106139">https://nptel.ac.in/courses/112106139</a>

	<b>Course Outcomes</b>	<b>CL</b>
<b>BME33606.1</b>	<b>Explain</b> the fundamental principles of measurement systems, to ensure accurate and reliable measurements.	4
<b>BME33606.2</b>	<b>Interpret</b> the principles of measurement instruments for linear and angular displacement.	3
<b>BME33606.3</b>	<b>Summarize</b> the operation of measurement instruments for pressure, temperature,	5
<b>BME33606.4</b>	<b>Apply</b> measurement standards and techniques, to ensure interchangeability and specify tolerances for precise engineering applications.	4
<b>BME33606.5</b>	<b>Evaluate</b> the use of advanced measurement instruments, to inspect complex parts.	5



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**Third Year (Semester-VI) B.Tech. Mechanical Engineering**

**BME33607: (PE-II) Ginning Process**

Teaching Scheme		Examination Scheme	
Lectures	3 Hr / Week	CT	30
Tutorials	-	CA	10
Total Credits	3	ESE	60
		Total	100 Marks
		Duration of ESE: 03 Hrs	

**Course Objectives:**

1	To provide fundamental knowledge of cotton history, species, fibre quality parameters, and the significance of ginning in the textile industry.
2	To explain the pre-ginning processes involved in handling, storing, drying, and cleaning raw cotton.
3	To familiarize students with the types, components, and working principles of different ginning machines and their operational parameters.
4	To study the bale making process, compression systems, and packaging standards for lint cotton.
5	To introduce automation techniques used in modern ginning plants for material handling and process control.

**Course Contents**

**Hours**

<b>Unit I</b>	History of Cotton, Different cotton species, hybrids & varieties in India & World, Fibre Quality Parameters, Trash Content, Ginning Percentage, Moisture content, Ginning Introduction, Development of Cotton Gin, Purpose of Ginning, Types of Ginning, Need of Textile Industry	<b>9</b>
<b>Unit II</b>	Pre Ginning Process, Storage of Raw Cotton, Feeding, Conveying and Drying, Pre and Post Cleaner (Cylinder Type LC)	<b>9</b>
<b>Unit III</b>	Ginning Process, Types of Ginning, Elements of Ginning Machine, Double Roller and Saw Gin, Rotobar Ginning, Production capacity of Ginning Machine, Lint and Cotton Seed Handling	<b>9</b>
<b>Unit IV</b>	Packing of Lint Cotton, Cotton Bale Making Process, Need of Compression, Type of Bale Press, Elements, Hydraulic versus Mechanical system of Compression, Lint handling and conditioning, Baling operation, Bale size, standard, Bale Packaging.	<b>9</b>
<b>Unit V</b>	Automation in Ginning Industry...Belt Conveyor, Screw conveyor, Pneumatic Conveying system, Fans, Centrifugal and axial, pull and push system, electrical and electronics control system	<b>9</b>

Text Books	
T.1	Double Roller Ginning Technology: Ginning Cotton in a Gentle Way by P. G. Patil, G. R. Anup, M. K. Sharma, Publisher: Bajaj Steel Industries Limited
T.2	Cotton Ginning: Technology, Trouble Shooting & Maintenance - V.G. Arude, S.K. Shukla, T.S. Manojkumar
Reference Books	
R.1	Cotton Science and Processing Technology: Gene, Ginning, Garment and Green Recycling - Publisher: Springer Nature Singapore
R.2	Cotton Ginnery Handbook United States Department of Agricultural
R.3	COTTON GINNERS HANDBOOK Development of the Cotton Gin Authors: Sidney E. Hughs, Gregory A. Holt, Carlos B. Armijo, Derek P. Whitelock, and Thomas D. Valco Pages: 34-43 Engineering and Ginning

	Course Outcomes	CL
<b>BME33607.1</b>	<b>Describe</b> the history, species, varieties, fibre quality parameters, and the need for ginning in the textile industry.	<b>3</b>
<b>BME33607.2</b>	<b>Explain</b> pre-ginning processes including cotton storage, feeding, conveying, drying, and cleaning operations.	<b>3</b>
<b>BME33607.3</b>	<b>Differentiate</b> between various types of ginning machines and <b>analyze</b> their components, working principles, and production capacities.	<b>3</b>
<b>BME33607.4</b>	<b>Evaluate</b> bale making processes, compression systems, and packaging standards for lint cotton.	<b>2</b>
<b>BME33607.5</b>	<b>Analyze and assess</b> the role of automation in ginning operations, including conveying systems, pneumatic transport, and control systems.	<b>2</b>



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### Third Year (Semester-VI) B.Tech. Mechanical Engineering

#### BME33608: (PE-II) Control System Engineering

Teaching Scheme		Examination Scheme	
Lectures	3 Hr/Week	CT	30 Marks
Tutorials	-	CA	10 Marks
Total Credits	3	ESE	60 Marks
		<b>Total</b>	100 Marks
			Duration of ESE: 03Hrs

#### Course Objectives:

1	To study modeling and transfer function of linear time-invariant system
2	To understand the stability, time domain specifications and tools
3	To understand classical controller/compensator design for linear system
4	To study frequency domain analysis of linear system
5	An introduction to state space approach and to understand the theory state transition matrix

#### Course Contents

		Hours
<b>Unit I</b>	<b>Introduction to Control System:</b> Need of control system, Open loop control and closed loop control, Significance of actuators and sensors, Control system Components (DC/AC servomotors, potentiometer, synchro), Mathematical representation of simple mechanical, electrical and electromechanical systems, Transfer function, Block diagram representation and reduction. Signal flow graph.	<b>(9)</b>
<b>Unit II</b>	<b>Time Response Analysis:</b> - Concept of transient response, steady state response and time response, standard test signals-type and order of system, steady state error analysis, static error constants, Time response of first and second order system, dominant poles, Time response specifications of second order system, Different types of Controllers (PD, PI, PID) Introduction of LAG, LEAD compensation.	<b>(9)</b>
<b>Unit III</b>	<b>Stability analysis &amp; Root locus:</b> Stability of control systems, condition of stability, characteristics equation, Routh Hurwitz criterion, special cases for determining relative stability. Root location and its effect on time response, elementary idea of root locus, effect of addition of pole and zero on proximity of imaginary axis.	<b>(9)</b>
<b>Unit IV</b>	<b>Frequency Domain Analysis:</b> - Concept of frequency response of a dynamical system. Construction of Bode plot, the stability margin on Bode plot and assessing close-loop stability. Construction of polar plot for a system. Nyquist stability criterion and stability margin. Effect of gain variation and addition of poles and zeroes on the frequency response plots.	<b>(9)</b>
<b>Unit V</b>	<b>State Variable Analysis:</b> - Concept of state, state variable and state model, Systems state model with physical variable, phase variable and canonical variables with state diagram, Transfer function from state model, Stability of state space model.	<b>(9)</b>

#### Text Books

T.1	Modern control system Engineering by K.Ogata , Publisher – Prentice Hall, India
T.2	Control System Analysis by Nagrath /Gopal , Publisher- Newage International
T.3	Automatic Control Systems by B.C. Kuo, Publisher – Prentice Hall, India

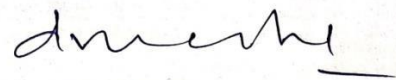
T.4	Control System Engineering by S.K. Bhattacharya, Publisher - Pearson
<b>Reference Books</b>	
R.1	Linear System Design by D'azzo and Houpis, Publisher- McGraw Hill
R.2	Control Systems, Principles & Design by M. Gopal Publisher – TMH (Tata Mc Graw Hill)
R.3	Control Systems Engineering by Samarajit Ghosh Publisher - Pearson

<b>Useful Links</b>	
1	<a href="https://www.youtube.com/watch?v=7LZSjgZzQw&amp;list=PLxn52v8fxX515tGzU1NAxRDkgqxK0k5UZ">https://www.youtube.com/watch?v=7LZSjgZzQw&amp;list=PLxn52v8fxX515tGzU1NAxRDkgqxK0k5UZ</a>
2	<a href="https://www.youtube.com/watch?v=39Ggoj2fQ2c&amp;list=PLxn52v8fxX515tGzU1NAxRDkgqxK0k5UZ&amp;index=2">https://www.youtube.com/watch?v=39Ggoj2fQ2c&amp;list=PLxn52v8fxX515tGzU1NAxRDkgqxK0k5UZ&amp;index=2</a>

	Course Outcomes	CL
<b>BME33608.1</b>	<b>Apply</b> block diagram reduction and signal flow graph techniques to simplify complex control systems	3
<b>BME33608.2</b>	<b>Explain</b> the time response characteristics of first and second-order systems, to determine system performance	4
<b>BME33608.3</b>	<b>Analyze</b> the stability of control systems using Routh-Hurwitz criterion to determine relative stability,	4
<b>BME33608.4</b>	<b>Summarize</b> the key concepts of frequency response analysis, and the use of Nyquist criterion to evaluate system stability	4
<b>BME33608.5</b>	<b>Apply</b> the state variable approach to model to determine the behavior of dynamic systems.	3



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**Third Year (Semester-VI) B. Tech. Mechanical Engineering**

**BME33609: (PE-III) Finite Element Method**

Teaching Scheme		Examination Scheme	
Lectures	3 Hr/Week	CT	30 Marks
Tutorials	-	CA	10 Marks
Total Credits	3	ESE	60 Marks
		<b>Total</b>	100 Marks
			Duration of ESE: 03Hrs

**Course Objectives:**

1	Understand the Fundamental Principles
2	Apply FEM to Solve Engineering Problems
3	Develop Computational Skills
4	Analyze and Interpret FEM Results
5	Enhance Problem-Solving and Research Skills

**Course Contents**

Course Contents		Hours
<b>Unit I</b>	Introduction to Engineering Analysis tool FEA and its application in Linear static Analysis and 2D problems, Study of Finite Element modeling and simulation Techniques, Use of FEA in structural vibration and thermal Analysis.	<b>(9)</b>
<b>Unit II</b>	Basics of FEM – Review of finite difference method, Initial value and boundary value problems Solution of Boundary Value problems: - weighted residual, Galerkin and Raleigh Ritz methods, Variational Method, Least square Methods. Introduction to meshless FEM, FEA and Linking mechanical design with FEA	<b>(9)</b>
<b>Unit III</b>	Two Dimensional Elements: Linear Triangular Elements, Rectangular Elements, Two Dimensional Field equations: Coordinate Systems, Isoparametric elements and numerical integration, Integral equations for the element Matrices, Heat transfer by conduction: One dimensional fins, two dimensional fins, and Long and convection Two Dimensional bodies.	<b>(9)</b>
<b>Unit IV</b>	FEA applications in Solid Mechanics: The axial force members, potential energy formulations. The Truss Element, Beam element, plane frame element, modeling of bolts for assembly, 3D problems.	<b>(9)</b>
<b>Unit V</b>	Two dimensional Elasticity: The displacement functions, Element matrices, Element Shape Functions: Evaluating shape functions FEM Computations Solution Methods, FEM Modeling and Preprocessing FEM Hardware and Postprocessing Survey of some FE Software Systems.	<b>(9)</b>

**Text Books**

T.1	Reddy, Junuthula Narasimha. An introduction to the finite element method. Vol.2, no.2.2. New York: Mc Graw-Hill, 1993.
T.2	Chandrupatla, Tirupathi R., Ashok D. Belegundu, T. Ramesh, and Chaitali Ray. Introduction to finite elements in engineering. Vol. 2. Upper Saddle River, NJ: Prentice Hall, 2002.
T.3	Desai, Chandrakant S., and John Fredrick Abel Introduction to the finite element method; a numerical method for engineering analysis. Van Nostrand Reinhold, 1971.

T.4	Zienkiewicz, Olek C., and Robert L. Taylor. The finite element method: Its basis and fundamentals.
<b>Reference Books</b>	
R.1	K.J. Bathe, Finite Element Procedures, Klaus-Jurgen Bathe 6. Singiresu S. Rao . Finite element method in engineering.
R.2	Cook, R.D., "Concepts and application in Finite Element Analysis", 3rd Ed, The Wiley & Sons
R.3	Dixit U.S., "Finite Element Methods for Engineers", Cengage Learning

<b>Useful Links</b>	
1	<a href="https://www.youtube.com/watch?v=tH1ygapKG2g&amp;list=PLSGws_74K018SmggufD-pbzG3thPIpF94&amp;index=2">https://www.youtube.com/watch?v=tH1ygapKG2g&amp;list=PLSGws_74K018SmggufD-pbzG3thPIpF94&amp;index=2</a>
2	<a href="https://www.youtube.com/watch?v=UOp6JEiJctA&amp;list=PLSGws_74K018SmggufD-pbzG3thPIpF94">https://www.youtube.com/watch?v=UOp6JEiJctA&amp;list=PLSGws_74K018SmggufD-pbzG3thPIpF94</a>

	<b>Course Outcomes</b>	<b>CL</b>
<b>BME33609.1</b>	<b>Apply</b> FEA modeling and simulation techniques to solve complex engineering problems	3
<b>BME33609.2</b>	<b>Apply</b> Different FEM Methods for the Solution of Boundary Value problems.	4
<b>BME33609.3</b>	<b>Summarize</b> the numerical methods for solving boundary value problems,	5
<b>BME33609.4</b>	<b>Apply</b> FEM Methods for the solution of 3D object	4
<b>BME33609.5</b>	<b>Evaluate</b> the effectiveness of FEM modeling and preprocessing techniques for two-dimensional elasticity problems	5

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### Third Year (Semester-VI) B. Tech. Mechanical Engineering

#### BME33610: (PE-III) Advanced Manufacturing Techniques

Teaching Scheme		Examination Scheme	
Lectures	3 Hr/Week	CT	30 Marks
Tutorials	-	CA	10 Marks
Total Credits	3	ESE	60 Marks
		<b>Total</b>	100 Marks
		Duration of ESE:03Hrs	

#### Course Objectives:

1	To understand the evolution and trends of advanced manufacturing and its comparison to traditional methods.
2	To explore additive manufacturing processes, their benefits, and limitations.
3	To learn about subtractive and hybrid manufacturing techniques.
4	To study advanced materials and processing techniques.
5	To explore the applications, quality control, and future trends in manufacturing.

#### Course Contents

Course Contents		Hours
<b>Unit I</b>	<b>Introduction to Advanced Manufacturing;</b> Overview of Manufacturing Evolution; Need for Advanced Manufacturing Techniques; Comparison with Traditional Manufacturing Processes; Technological Advancements Driving Manufacturing Innovation; Emerging Trends in Advanced Manufacturing; Advantages of Advanced Manufacturing Techniques; Future Scope and Challenges	<b>(9)</b>
<b>Unit II</b>	<b>Additive Manufacturing and 3D Printing: Introduction to Additive Manufacturing (AM);</b> Evolution and Technological Improvements; AM Process and Classification; Materials Used in Additive Manufacturing; Advantages of Additive Manufacturing; Limitations of Additive Manufacturing; Additive vs. Conventional Manufacturing Processes	<b>(9)</b>
<b>Unit III</b>	<b>Subtractive and Hybrid Manufacturing;</b> Introduction to Subtractive Manufacturing; CNC Machining and Automation; Electric Discharge Machining (EDM); Electrochemical Machining (ECM); Laser Beam Machining; Water Jet Cutting; Hybrid Manufacturing Systems; Applications and Advantages of Subtractive and Hybrid Processes	<b>(9)</b>
<b>Unit IV</b>	<b>Advanced Processing and Materials;</b> Introduction to Advanced Material Processing, Advanced Material Forming Techniques, Powder Metallurgy and Sintering, Additive Manufacturing Materials, High-Performance Materials in Manufacturing, Ceramic and Composite Materials, Non-Traditional Welding and Joining Methods, Future Trends in Materials Processing	<b>(9)</b>
<b>Unit V</b>	<b>Applications, Quality, and Future Trends;</b> Applications in Aerospace, Automotive, Biomedical, and Electronics, Digital Manufacturing and Industry 4.0, Smart Factories and the Role of IoT, Cyber-Physical Systems and Automation, Quality Control and Inspection Techniques, Process Control and Optimization, Sustainability and Green Manufacturing, Future Trends in Manufacturing Technologies	<b>(9)</b>

#### Text Books

T.1	"Introduction to Manufacturing Processes" by Mikell P. Groover
T.2	"Additive Manufacturing: Materials, Processes, Quantifications, and Applications" by Kun Zhou

T.3	"Modern Machining Technology" by Chandra Sekhar
<b>Reference Books</b>	
R.1	Understanding Additive Manufacturing Rapid Prototyping · Rapid Tooling · Rapid Manufacturing Andreas Gebhardt, Hanser Publishers, Munich Hanser Publications, Cincinnati
R.2	Additive Manufacturing of Metals: The Technology, Materials, Design and Production , Li Yang Keng Hsu · Brian Baughman Donald Godfrey · Francisco Medina Mamballykalathil Menon SoerenWiener, Springer Series in Advanced Manufacturing

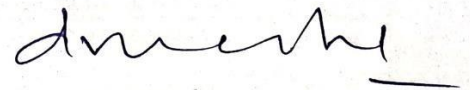
<b>Useful Links</b>	
1	<a href="https://onlinecourses.nptel.ac.in/noc21_me115/preview">https://onlinecourses.nptel.ac.in/noc21_me115/preview</a>
2	<a href="https://onlinecourses.nptel.ac.in/noc20_me50/preview">https://onlinecourses.nptel.ac.in/noc20_me50/preview</a>

	<b>Course Outcomes</b>	<b>CL</b>
<b>BME33610.1</b>	<b>Interpret</b> the differences between traditional and advanced manufacturing processes, to find the benefits of adopting advanced manufacturing techniques.	3
<b>BME33610.2</b>	<b>Summarize</b> the key concepts of Additive Manufacturing (AM) and 3D Printing, to find advantages, limitations, and comparison with conventional manufacturing processes.	5
<b>BME33610.3</b>	<b>Analyze</b> subtractive manufacturing processes, to determine their applications and advantages.	4
<b>BME33610.4</b>	<b>Interpret</b> the properties of advanced materials, for requirement in various manufacturing industries.	3
<b>BME33610.5</b>	<b>Explain</b> the concepts of smart factories, in modern manufacturing, for process optimization.	4



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### Third Year (Semester-VI) B.Tech. Mechanical Engineering

#### BME33611: (PE-III) Operation Research

Teaching Scheme		Examination Scheme	
Lectures	3 Hr/Week	CT	30 Marks
Tutorials	-	CA	10 Marks
Total Credits	3	ESE	60 Marks
		<b>Total</b>	100 Marks
		Duration of ESE: 03 Hrs	

#### Course Objectives:

1	To study the various OR tools,
2	To apply appropriate model to the given situation.
3	To Formulate the problem.
4	To Solve and analyze the problem
5	To mathematical models and solve management problems.

#### Course Contents

	Hours
<b>Unit I</b>	Introduction to O.R. & basic O.R. Models, Characteristics, phases & Methodology of O.R., Limitations & Applications. Linear Programming:-Introduction, Linear programming problem formulation, LPP Solution by Graphical Method, Simplex Method, Principle of Duality & Formulation of Model only, Sensitivity Analysis Concept Only.
<b>Unit II</b>	Formulation of transportation model, Basic feasible solution using different methods (North- West corner, Least Cost, Vogel's Approximation Method) Optimality Methods, Unbalanced transportation problem, Variants in Transportation Problems. Formulation of the Assignment problem, unbalanced assignment problem, typical assignment & travelling salesman problem
<b>Unit III</b>	Replacement Models-Concept of equivalence, Interest Rate, Present worth, economic evaluations of Alternatives, Group replacement models. Inventory Control Models- Introduction and inventory management concepts, Economic Order Quantity model (EOQ), Economic Production Quantity model (EPQ), model for purchase allowing for shortages, ABC analysis.
<b>Unit IV</b>	Drawing of Network, CPM & PERT, probability of completion of project, Cost Analysis of Project, and Concept of Crashing. Allocation & updating of Network.
<b>Unit V</b>	Sequencing Model- Introduction, Sequencing Model n job two machines problem, n job 3 machines problem, 2 jobs m machine problem. Simulations -Concept, applications in waiting line situations, inventory and network. Queuing models- Poisson arrivals and Exponential service times -Single channel models (MM1) and Multi channel models. (No derivation expected)

#### Text Books

T.1	Operation Research, Heera & Gupta, S Chand Publications
T.2	Operation Research, J K Sharma, Mc Millian Publications
T.3	Operation Research, S D Sharma, Kedarnath Ramnath & Co.

#### Reference Books

R.1	Operation Research, Hamdy Taha, Prentice Hall
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R.2	Operation Research, Liberman, Mc GrawHillPublications
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Useful Links	
1	<a href="https://nptel.ac.in/courses/110/106/110106062/">https://nptel.ac.in/courses/110/106/110106062/</a>
2	<a href="https://examupdates.in/operation-research-notes/">https://examupdates.in/operation-research-notes/</a>

	Course Outcomes	CL
<b>BME33611.1</b>	<b>Solve</b> linear programming problems using graphical to formulate dual models.	3
<b>BME33611.2</b>	<b>Determine</b> the optimal solution to transportation problems using North-West corner method,	4
<b>BME33611.3</b>	<b>Apply</b> an optimal replacement period of equipment or machine to determine the value of the given Inventory Model.	3
<b>BME33611.4</b>	<b>Illustrate</b> project networks using CPM and PERT techniques, to determine project completion probability.	3
<b>BME33611.5</b>	<b>Summarize</b> the key concepts of queuing theory, to solve real-world problems.	5





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<b>Third Year (Semester-VI) B. Tech. Mechanical Engineering</b>			
<b>BME33612: (PE-III) Industrial Robotics</b>			
<b>Teaching Scheme</b>		<b>Examination Scheme</b>	
<b>Lectures</b>	3 Hr/Week	<b>CT</b>	30 Marks
<b>Tutorials</b>	-	<b>CA</b>	10 Marks
<b>Total Credits</b>	3	<b>ESE</b>	60 Marks
		<b>Total</b>	100 Marks
		Duration of ESE:03Hrs	
<b>Course Objectives:</b>			
1	To introduce the functional elements of robotics.		
2	To impart knowledge on robot end effector and grippers.		
3	To introduce the dynamics and control of manipulators in robotics.		
4	To understand the basic concepts of robotic sensors used in industries.		
5	To understand the cell layouts of robots and their interfaces.		
<b>Course Contents</b>			<b>Hours</b>
<b>UnitI</b>	Basic concepts :-Brief history-Types of Robot–Technology-Robot classifications and specifications- Design and control issues-Variou manipulators–Sensors- workcell- Programming languages.		<b>(9)</b>
<b>UnitII</b>	Robot send- effectors- classification o fend- effectors, mechanical grippers, hooking or lifting grippers, grippers for molten metal"s, plastics, vacuum cups ,magnetic grippers, electrostatic grippers, multiple grippers, internal & external grippers, drives systems for gripers, active & Passive grippers.		<b>(9)</b>
<b>Unit III</b>	Direct and inverse kinematics:-Mathematical representation of Robots-Position and orientation -Homogeneous transformation Various joints-Representation using the Denavit Hattenberg parameters- Degrees off reedom- Direct kinematics-Inverse kinematics- SCARA robots- Solvability – Solution methods-Closed form solution.		<b>(9)</b>
<b>UnitIV</b>	Robot Sensors: Scheme of robotic sensors, contact type sensors, force, torque, touch, position, velocity sensors, non-contact type sensors, electro-optical imaging sensors, proximity sensors, range imaging sensors, robot environment and robot input/ output interfaces, machine intelligence, Safety measures in robots.		<b>(9)</b>
<b>UnitV</b>	Robot cell layouts, multiple robots and machine interface, other considerations in work cell design, work cell control, interlocks, error detection and recovery, Quantitative Techniques for economic performance of robots: Robot investment coats, robot operating expenses. General considerations in robot material handling, material transfer applications, pick and place operations, machine loading and unloading, die casting, plastic molding, forging, machining operations, stamping press operations using robots.		<b>(9)</b>
<b>Text Books</b>			
T.1	K. MittalandI. J.Nagrath, Robotics and Control,Tata Mc Graw Hill, New Delhi,4thReprint, 2005		
T.2	M.P. Groover, M. Weiss,R. N. Nageland N.G. Odrej, Industrial Robotics, Mc Graw-Hill Singapore, 1996.		
T.3	JohnJ.Craig, Introduction to Robotics Mechanics and Control, Third edition, Pears on Education		

## Reference Books

R.1	Ashitava Ghoshal, Robotics- Fundamental Concepts and Analysis",Oxford University Press, Sixth impression, 2010.
R.2	K. K. Appu Kuttan, Robotics, I K International, 2007. Edwin Wise, Applied Robotics,Cengage Learning.
R.3	R. D .Klafter,T.A. Chmielowski and M.Negin, Robotic Engineering– An Integrated Approach, Prentice Hall of India,New Delhi,1994.
R.4	B.K. Ghosh, Control in Robotics and Automation: Sensor Based Integration, Allied Publishers, Chennai, 1998.
R.5	S. Ghoshal,“Embedded Systems & Robotics”–Projects usingthe8051Microcontroller”, Cengage Learning, 2009.

## Useful Links

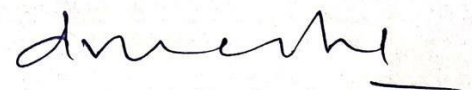
1	<a href="https://onlinecourses.nptel.ac.in/noc23_me143/">https://onlinecourses.nptel.ac.in/noc23_me143/</a>
2	<a href="https://archive.nptel.ac.in/courses/112/105/112105249/">https://archive.nptel.ac.in/courses/112/105/112105249/</a>
3	<a href="https://www.youtube.com/watch?v=OSrMXiaWPZY&amp;list=PLXDsvE7qtfNf_N99hJZbdTEM001mOii6_&amp;index=1">https://www.youtube.com/watch?v=OSrMXiaWPZY&amp;list=PLXDsvE7qtfNf_N99hJZbdTEM001mOii6_&amp;index=1</a>

	Course Outcomes	CL
<b>BME33612.1</b>	<b>Analyze</b> the design and control issues of robots, to determine their impact on robot performance.	4
<b>BME33612.2</b>	<b>Interpret</b> the role of drive systems and control mechanisms in robot end-effectors, to find impact on robotic performance.	4
<b>BME33612.3</b>	<b>Summarize</b> the methods for solving direct and inverse kinematics problems in robotics,	4
<b>BME33612.4</b>	<b>Discuss</b> the types of robot sensors for its applications.	3
<b>BME33612.5</b>	<b>Illustrate</b> the application of robots in material handling, including quantitative techniques for determining economic performance	3



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**Third Year (Semester-VI) B. Tech. Mechanical Engineering**

**BCS33614: Artificial Intelligence**

Teaching Scheme		Examination Scheme	
Lectures	4 Hr/Week	CT	-
Tutorials	-	CA	25 Marks
Total Credits	2	ESE	25 Marks
		<b>Total</b>	<b>50 Marks</b>
		<b>Duration of ESE: 02 Hrs</b>	

**Course Objectives:**

1	To introduce students to basic Python programming and essential tools used in AI Implementation.
2	To develop foundational skills in loading, understanding, and preprocessing simple datasets.
3	To enable students to apply basic Machine Learning algorithms for prediction and classification tasks.
4	To familiarize students with basic model evaluation techniques used in AI.
5	To build confidence in executing small-scale AI mini projects using beginner-friendly methods.

Sr. No.	List of Experiment	CO
1	Introduction to Google Colab / Jupyter Notebook environment.	CO1
2	Writing basic Python code for AI (variables, loops, functions).	CO1
3	Loading a simple dataset (CSV) using Pandas.	CO1
4	Displaying dataset information and summary statistics.	CO2
5	Plotting basic graphs (line, bar, scatter) using Matplotlib.	CO2
6	Handling missing values in datasets (drop/fill).	CO2
7	Splitting data into training and testing sets.	CO3
8	Implementing a simple Linear Regression model.	CO3
9	Implementing a basic Logistic Regression classifier.	CO3
10	Evaluating model performance using accuracy score.	CO4
11	Creating a confusion matrix for classification results.	CO4
12	Implementing a simple Decision Tree classifier.	CO4
13	Building a very simple Neural Network (Keras/TensorFlow).	CO5
14	Performing basic sentiment analysis with a small text dataset.	CO5
15	Mini Project: Train a simple model and generate predictions.	CO5

**Text Books**

T.1	Artificial Intelligence: A Modern Approach (Beginners Edition Concepts), Stuart Russell & Peter Norvig, Prentice Hall
T.2	Artificial Intelligence for Beginners, Oliver Theobald, Independent Publishing

**Reference Books**

R.1	Introduction to Artificial Intelligence, Wolfgang Ertel, Springer
R.2	Practical Artificial Intelligence with Python, Arun Kumar / Packt

## Useful Links

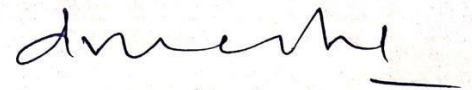
1 <https://nptel.ac.in/courses/106102220>

	Course Outcomes	CL
<b>BCS33614.1</b>	<b>Demonstrate</b> the ability to use Python and AI tools to perform basic data loading, preprocessing, and visualization tasks.	3
<b>BCS 33614.2</b>	<b>Analyze</b> simple datasets and apply appropriate beginner-level Machine Learning models for prediction and classification.	3
<b>BCS 33614.3</b>	<b>Construct</b> basic AI workflows using Python libraries to train, test, and validate ML models.	3
<b>BCS 33614.4</b>	<b>Differentiate</b> basic model performance metrics (accuracy, confusion matrix) to interpret results effectively.	4
<b>BCS 33614.5</b>	<b>Summarize</b> introductory AI applications through hands-on exercises and a simple AI mini project.	5

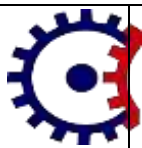


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**Third Year (Semester-VI) B. Tech. Mechanical Engineering**

**BME33604: Modelling And Simulation Using Software**

Teaching Scheme		Examination Scheme	
Lectures	2 Hr/Week	CT	-
Tutorials	-	CA	25 Marks
Total Credits	1	ESE	25 Marks
		Total	50 Marks
		Duration of ESE : 02 Hrs	

**Course Objectives:**

- 1 Understand the fundamentals of 3D modeling and simulation software (CREO and ANSYS).
- 2 Apply design tools in CREO to create detailed part and assembly models.
- 3 Simulate and analyze real-world mechanical problems using ANSYS.
- 4 Integrate CAD and FEA tools for product development and testing.
- 5 Develop skills for industry-based design validation and optimization.

Sr. No.	List of Experiment	CO
1	Introduction to CREO: Sketching and Part Modeling of a Mechanical Component	CO1
2	Advanced 3D Modeling in CREO: Gear, Coupling, or Crankshaft	CO1
3	CREO Assembly Modeling: Assemble a Shaft-Bearing-Housing System	CO2
4	Drafting and Detailing in CREO: 2D Drawing Extraction from 3D Model	CO2
5	Introduction to ANSYS: Geometry Import and Meshing Techniques	CO3
6	Static Structural Analysis in ANSYS: Cantilever Beam under Load	CO3
7	Thermal Analysis in ANSYS: Heat Transfer through Fin	CO3
8	Modal Analysis in ANSYS: Natural Frequency of a Bracket	CO4
9	Stress Analysis of Assembly Model: Imported from CREO to ANSYS	CO4
10	Mini-Project: Design and Analysis of a Mechanical Part/Assembly (e.g., Chassis Frame or Connecting Rod)	CO5


**Text Books**

T.1	"Creo Parametric 10.0 for Engineers and Designers" – Sham Tickoo
T.2	"PTC Creo Parametric 10.0 Tutorial" – Kristin Eckstein, Roger Toogood
T.3	"Learning Creo Parametric 10.0" – Randy Shih

T.4	"Introduction to Finite Element Analysis Using ANSYS" – Saeed Moaveni
<b>Reference Books</b>	
R.1	Practical Finite Element Analysis Author: Nitin S. Gokhale et al. Publisher: Finite to Infinite
R.2	ANSYS Workbench 2023 R1: A Tutorial Approach Author: Prof. Sham Tickoo Publisher: CAD/CIM Technologies


<b>Useful Links</b>	
1	<a href="https://nptel.ac.in/courses/112104193">https://nptel.ac.in/courses/112104193</a>
2	<a href="https://nptel.ac.in/courses/112102101">https://nptel.ac.in/courses/112102101</a>

	<b>Course Outcomes</b>	<b>CL</b>
<b>BME33604.1</b>	<b>Demonstrate</b> the ability to model complex mechanical components using CREO, to enhance knowledge of advanced features.	3
<b>BME33604.2</b>	<b>Analyze</b> the assembly modeling and drafting capabilities of CREO by creating complex assemblies for learning practical skills.	3
<b>BME33604.3</b>	<b>Construct</b> 3D models and assemblies using CREO to perform static analysis using ANSYS.	3
<b>BME33604.4</b>	<b>Differentiate</b> material behavior under various load conditions to find simulation results.	4
<b>BME33604.5</b>	<b>Summarize</b> engineering components through integrated use of CAD and FEA tools to determine optimization of Assembly model.	5



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**Third Year (Semester-VI) B. Tech. Mechanical Engineering**

**BME33605: Modelling And Tool Path Generation using Software**

Teaching Scheme		Examination Scheme	
Lectures	2 Hr/Week	CT	-
Tutorials	-	CA	25 Marks
Total Credits	1	ESE	25 Marks
		Total	50 Marks
		Duration of ESE: 02 Hrs	

**Course Objectives:**

1	To introduce basic 3D modelling using Fusion 360.
2	To teach simple sketching and feature creation.
3	To familiarize students with basic CNC toolpaths.
4	To enable students to simulate and verify basic toolpaths.
5	To provide hands-on experience in generating simple G-code.

Sr. No.	List of Experiment	CO
1	Introduction to Fusion 360 interface	CO1
2	Basic 2D sketching tools and constraints	CO1
3	Basic 3D modelling using Extrude, Revolve, Fillet, etc.	CO1
4	Creating simple mechanical parts	CO1
5	Importing 2D drawings and converting to 3D models	CO2
6	Creating basic assemblies	CO2
7	Introduction to CAM/Manufacture workspace	CO2
8	Creating 2D milling toolpaths (Facing, Pocket, Contour)	CO3
9	Creating drilling toolpaths	CO3
10	Creating a basic tool library	CO3
11	Creating simple 3D finishing toolpaths	CO4
12	Engraving text on a part	CO4
13	Running toolpath simulation	CO4
14	Generating and exporting G-code	CO5
15	Mini project: Model + Toolpath + Simulation	CO5

**Text Books**

T.1	CAD/CAM: Computer-Aided Design and Manufacturing, By Mikell P. Groover, McGraw-Hill Education
T.2	Autodesk Fusion 360 Industrial and Mechanical Design, By Paul Tran, SDC Publications

**Reference Books**

R.1	CNC Machining Handbook: Building, Programming, and Implementation, By Alan Overby
R.2	Autodesk Fusion 360: A Power Guide for Beginners and Intermediate Users (4th Edition). CAD Artifex. Dogra, Sandeep.

**Useful Links**1 <https://nptel.ac.in/courses/112104289>

	<b>Course Outcomes</b>	<b>CL</b>
<b>BME33605.1</b>	<b>Demonstrate</b> the ability to model mechanical components using Fusion 360, applying essential sketching and 3D modelling features for manufacturing preparation.	3
<b>BME33605.2</b>	<b>Analyze</b> the CAM workspace of Fusion 360 by generating 2D and 3D toolpaths to develop practical CNC machining skills.	3
<b>BME33605.3</b>	<b>Construct</b> 3D models and corresponding machining setups in Fusion 360 to simulate toolpaths and verify manufacturability.	3
<b>BME33605.4</b>	<b>Differentiate</b> machining strategies, cutter selections, and toolpath types under varying manufacturing requirements to improve machining output.	4
<b>BME33605.5</b>	<b>Summarize</b> the complete workflow from CAD modelling to CAM simulation and G-code generation using Fusion 360 to optimize manufacturing processes.	5

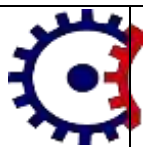


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**Third Year (Semester-VI) B. Tech. Mechanical Engineering**

**BME33613: Internal Combustion Engine Lab**

Teaching Scheme		Examination Scheme	
Lectures	2Hr/Week	CT	-
Tutorials	-	CA	25 Marks
Total Credits	1	ESE	25 Marks
		Total	50 Marks
		Duration of ESE : 02 Hrs	

**Course Objectives:**

1	To learn the basic concept of I C Engine	
2	To enhance the knowledge of IC engine	
3	To share complete knowledge of type of fuels used in IC engines and the fuel supply systems	
4	To describe combustion phenomena in IC engines	
5	To explain the different performance analysis of IC engines	
Sr. No.	List of Experiment	CO
1	Assemble/Dismantle Multi cylinder Petrol Engine.	CO1
2	Assemble/Dismantle Multi cylinder Diesel Engine.	CO1
3	Demonstrate The Significance Of Fuel Injection And Ignition Systems Of IC Engine	CO2
4	Demonstrate The Importance of Different types of Carburetor used in Petrol Engine	CO2
5	Demonstrate The Importance Of Engine Cooling And Lubrication System Of IC Engine	CO3
6	To study the Actual valve timing diagram of 4 stroke petrol engine.	CO4
7	Perform Load Test On Petrol Engine Test Rig To Prepare The Heat Balance Sheet And Plot Performance Curve	CO4
8	Perform Morse Test on the Petrol Engine Test Rig	CO4
9	To study the Actual valve timing diagram of 4 stroke diesel engine.	CO5
10	Perform Load Test On Diesel Engine Test Rig To Prepare The Heat Balance Sheet And Plot Performance Curve	CO5

**Text Books**

T.1	Internal Combustion Engine by V Ganeshan, McGraw Hill Education Pvt. Ltd.
T.2	Internal Combustion Engine by R. K. Rajput, Laxmi Publication
T.3	Internal Combustion Engines by V. M. Domkundwar, Dhanpat Rai Publications (P) Ltd.
T.4	Internal Combustion Engine by M. L. Mathur and R. P. Sharma, Dhanpat Rai Publications (P) Ltd

**Reference Books**

R.1	Internal Combustion Engines, E. Obert, Intex educational publication.
R.2	Internal Combustion Engine fundamental by John Heywood, Tata MCGraw Hill Publication

### Useful Links

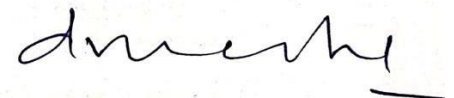
1	<a href="https://nptel.ac.in/courses/112104033">https://nptel.ac.in/courses/112104033</a>
2	<a href="https://nptel.ac.in/courses/112103262">https://nptel.ac.in/courses/112103262</a>

	Course Outcomes	CL
<b>BME33613.1</b>	<b>Demonstrate</b> the ability to safely assemble and dismantle a multi-cylinder petrol engine,	3
<b>BME33613.2</b>	<b>Demonstrate</b> knowledge of carburetors used in petrol engines, to aware importance in air-fuel mixture preparation.	3
<b>BME33613.3</b>	<b>Analyze</b> the engine cooling and lubrication systems of IC engines, to know their key components, functions,	3
<b>BME33613.4</b>	<b>Evaluate</b> the performance of a multi-cylinder petrol engine using the Morse test	3
<b>BME33613.5</b>	<b>Summarize</b> the performance characteristics of a diesel engine under varying load conditions, to find heat balance sheet and performance curves	5



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**Third Year (Semester-VI) B. Tech. Mechanical Engineering**

**BME33614: Mechatronics & Robotics Lab**

Teaching Scheme		Examination Scheme	
Practical	2Hr/Week	-	-
	-	CA	25
Total Credits	1	ESE	25
		Total	50 Marks
		Duration of ESE: 02 Hrs	

**Course Objectives:**

<b>1</b>	To familiarize students with the identification and application of electronic components, sensors, and actuators used in Mechatronics systems
<b>2</b>	To enhance the understanding of industrial automation by analyzing and executing automation task using standard model
<b>3</b>	To apply PLC programming concepts for automation tasks including bottle filling, lift control, and water level management.
<b>4</b>	To demonstrate the use of electro-pneumatic and hydraulic systems for motion control in industrial automation
<b>5</b>	To develop the ability to compare various industrial robots based on their configuration and degrees of freedom.

Experiment no.	Name of Experiment	CO
<b>1</b>	Interpret the characteristics and functionality of solid-state electronic devices for classification and application in electronic circuits.	<b>CO1</b>
<b>2</b>	Selection of different types of sensors and actuators in mechatronic systems with its application.	<b>CO2</b>
<b>3</b>	Develop a ladder logic program using PLC for a bottle filling plant as part of a Mechatronic system	<b>CO3</b>
<b>4</b>	Construct a ladder logic-based PLC program for a Water Level Controller and demonstrate its integration in a Mechatronic system.	<b>CO3</b>
<b>5</b>	Implementation of ladder logic program using PLC for a Lift Control System in the context of Mechatronic automation.	<b>CO3</b>
<b>6</b>	Demonstration of Electro Pneumatic Systems	<b>CO4</b>
<b>7</b>	Demonstration of Electro Hydraulic Systems	<b>CO4</b>
<b>8</b>	Comparative Study of Industrial Robots Based on Configuration and Degrees of Freedom. (Articulate, SCARA, Cartesian, Cylindrical, Delta)	<b>CO5</b>
<b>9</b>	Study of Articulated Robot Configuration and Degrees of Freedom	<b>CO5</b>
<b>10</b>	Performance of Pick-and-Place Operation Using Articulated Robot	<b>CO5</b>

**Text Books**

T.1	Mechatronics - Integrated Mechanical Electronics System, K.P. Ramachandran, Wiley India Pvt. Ltd. New Delhi
T.2	Mechatronics & Microprocessors, K.P. Ramachandran, Wiley India Pvt. Ltd., New Delhi
T.3	Mechatronics, Bolton W, Pearson Education, Second Edition, 1999.

**Reference Books**

R.1	Pneumatic Tips, Festo K G, Festo, Germany, 1987
R.2	Mechatronics: Introduction, Robert H Bishop, Taylor and Francis, 2006.

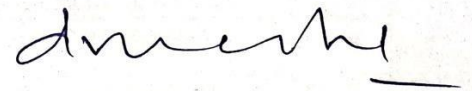
Useful Links	
1	<a href="https://archive.nptel.ac.in/courses/112/107/112107298/">https://archive.nptel.ac.in/courses/112/107/112107298/</a>
2	<a href="https://nptel.ac.in/courses/112103174">https://nptel.ac.in/courses/112103174</a>

	Course Outcomes	CL
<b>BME33614.1</b>	<b>Interpret</b> the characteristics and functionality of solid-state electronic devices, to get classification, and application in electronic circuits.	3
<b>BME33614.2</b>	<b>Illustrate</b> the selection and application of sensors to, highlight their functionality and importance in system design.	3
<b>BME33614.3</b>	<b>Demonstrate</b> the ladder logic programming using PLC for automation.	3
<b>BME33614.4</b>	<b>Demonstrate</b> knowledge of electro-hydraulic systems, to gain knowledge of design and troubleshoot hydraulic circuits.	3
<b>BME33614.5</b>	<b>Summarize</b> the performance characteristics of articulated robots in pick-and-place operations, to influence their performance.	5



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